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## B4795-B **Boct Brushless ESC Manual**

Over tempcrature protection

Motor will be intermittently turned

off & on when the temperature

reaches around (98±3~5)°c

### 規格

- 1.Input Voltage:7.2V~8.4V(NI-CD/MH) 7.4V(LI-PO) 6.6V(LI-FE)

   2.Output:Rating 150A, Peak:750A
   3.P.W.M:9.5KI
  3.P.W.M:9.5KHz
- 4.Out max power: 45A/7.2V(MAX 324 W)
- 5.Size/Weight:26.4mmX44.4mmX13.6mm/46g 6.BEC:5V 2A
- 7.MOTOR:540S(360×50)Motor(A:<7.4V;Support 2500KV↓Motor
  - ,B:11.1V Suport 2000KV motor)

### 注意事項

- 1.Avoid touching ESC heat sink or motor casing right after operation for not burning your body or skin.
- 2.To avoid poor contact or overheat melting of connector and power abnormal cut off be sure to always use better current rated connector & wires while replacing the original ESC connector or elongating the connecting wires.
- 3.Connect the battery pack just before driving, disconnect & take it out the car immediately after termination.Don't soldrt ESC wires directly to the battery.A proper connector is a must to be used in brtween.
- 4.When using programming card(B6091-1), please turn off ESC Power and take the servo wire out of the receiver, then insert the set up card according to the electrode sign on the card. After setting programming card, needs to turn off power at the same time, then take servo wire into of the receiver.
- 5.Always make surt connecting the ESC to a proper power source that has the correct voltage & polarity.Incorrect voltages or reversed polarity will damage the ESC.Don't solder ESC wires directly to the battery. A proper connector is a must to be used in between.

used in bitween.		
Matarapacification		
Motor specification	Battery Volt 7.2V 7.4V 6.6V	
	AUTO Initial Detected voltage x70%	
	NI-CD/NI-MH 5.4V	
	LI-PO 6.0V	
	LI-FE 4.8V	
ESC wiring diagram		
	Red Power wer(+)	
	Water Intake	
Receiver plug,plug into Ch2	utaba receiver Rrceiver plug atten AL12-B Poart 30,5 Po	
Receiver plug,plug into Ch2 Polarities only match with JR & Futaba receiver Be careful to check for other brand receivers		
before plugging.		
	Black Power wer(-) Water Outlet →	
Test of throttle direction	n coincidence	
1 Wiring ESC	2 3 ESC denotes a 4 Denoted by	
according to above diagram.	Switch on the sound and starts another confirmation sound after succeed in	
	setting neutral.	
quickly p	he left test sequence right above setting is completed Push the throttle trigger forwards, ull the throttle trigger backwards & hold it. If the system keeps braking, the throttle direction test is ok.	
	e, if it drives reversely, the throttle and ESC forward direction does not coincide with each other. he throttle reversing switch of the transmitter, turn off & then turn on the ESC power again will correct the proble	
Neutral→forward→backward		
Safe gear ratio test	stly, trial running starting with a small gear motor for 2~3 minutes, measure the temperatures of both	
Esc & motor. If both temperatures are close with each other, they are at good match. The gear ratio can then be properly adjusted to optimum according to the features of the courses. However, It's very		
important to always keep both temperatures under 100 °c, while adjusting the gear ratio. Otherwise the demagnetization of the motor will happen, the motor efficiency will drop dramatically & the temperature will		
Input voltage      resistance      waste current      also raise up very quickly. Most battery power is now wasted on heat nothing on motor efficiency.        7.2V      0.18Ω      40A		
Bu	s ok to replace a higher gear ratio or a higher KV motor while the temperature of the ESC is under 80 ° t it should be done according to para 6 described, from small to bigger. Unless the kv value of the ginal motor is very low enough, It should replace a motor with lower kv value when the input battery	
	ginal motor is very low charger, it should replace a motor with lower ky value when the input barged while	

voltage is changed to a higher level. The ESC will be burnt if the motor doesn't be properly changed while input voltage is changed. See example by the side of lest on the current changed inside motor while input

voltage is changed.

 $(V/R=1 \ 11.1V/0.18\Omega=61.6A)$ 

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### 20100408